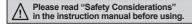
Single Display, PID Control Temperature Controller

Features

- Realizes ideal temp. controlling with newly developed PID control algorithm and 100ms high speed sampling
- Built-in relay output or SSR output selectable
 Enables to phase control and cycle control with SSR drive output (SSRP function)
- Dramatically increased visibility using wide display part
- Mounting space saving with compact design : Approx. 38% reduced size compared with existing model (depth-based)
- SV/PV deviation indicatable





Ordering Information

T C 4	1 S]-[1	4 R		
			Control output	N	Indicator - Without control output
				R	Relay output + SSR drive output ^{x1}
			Power supply	2	24VAC 50/60Hz, 24-48VDC
				4	100-240VAC 50/60Hz
			Alarm output	N	No alarm output
		L	Alaim output	1	Alarm 1 output
				2	Alarm 1 output + Alarm 2 output**2
				S	DIN W48×H48mm (terminal block type)
		٠.		SP	DIN W48×H48mm (11-pin plug type) ^{×3}
	Ľ	Size		Y	DIN W72×H36mm
				М	DIN W72×H72mm
				Н	DIN W48×H96mm
				W	DIN W96×H48mm
	<u> </u>			L	DIN W96×H96mm
	Digit			4	9999 (4-digit)
Settir	ng type			C	Set by touch switch
Item				T	Temperature controller

- X1: In case of the AC voltage model, SSR drive output method (standard ON/OFF control, cycle, control, phase control) is available to
- ※2: It is unavailable for TC4SP, TC4Y.v
- **3: 11-pin socket (PG-11, PS-11(N)) for TC4SP: sold separately.

Specifications

- Sheci										
Series		TC4S	TC4SP	TC4Y	TC4M	TC4W	TC4H	TC4L		
Power	AC power	100-240VAC~	00-240VAC∼ 50/60Hz							
supply	AC/DC power	24VAC~ 50/60	4VAC~ 50/60Hz, 24-48VDC==							
Allowable voltage range		90 to 110% of r	ated voltage							
Power	Power AC power		Max. 5VA (100-240VAC~ 50/60Hz)							
consumption	AC/DC power	Max. 5VA (24V	Max. 5VA (24VAC∼ 50/60Hz), max. 3W (24-48VDC)							
Display meth	od	7-segment (red), other display (green, yellow, red) LED								
Character siz	e (W×H)	7.0×15.0mm		7.4×15.0mm	9.5×20.0mm	9.5×20.0mm	7.0×14.6mm	11.0×22.0mm		
Input tupo	RTD	DPt100 Ω , Cu50 Ω (allowable line resistance max. 5 Ω per a wire)								
Input type	Thermocouple	K(CA), J(IC), L(IC)								
Display	RTD		At room temperature (23°C±5°C): (PV ±0.5% or ±1°C, select the higher one) ±1-digit Out of room temperature range: (PV ±0.5% or ±2°C, select the higher one) ±1-digit							
accuracy*1	Thermocouple		,	ge: (PV ±0.5% 0 curacy standard.	- /	ie nigner one) ±	i -uigit			

- \times 1: Thermocouple L(IC) type, RTD Cu50 Ω
 - At room temperature (23°C ±5°C): (PV ±0.5% or ±2°C, select the higher one) ±1-digit
 - Out of room temperature range: (PV ±0.5% or ±3°C, select the higher one) ±1digit

In case of TC4SP Series, ±1°C will be added.

J-120 Autonics

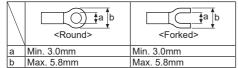
Specifications

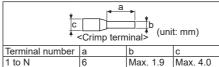
Series		TC4S	TC4SP	TC4Y	TC4M	TC4W	TC4H	TC4L
Control	Relay	250VAC~ 3	A, 30VDC== 3A	A, 1a				
output	SSR	12VDC== ±2	V 20mA Max.					
Alarm outp	ut	AL1, AL2 Re	lay: 250VAC 1	A 1a (※TC4S	SP, TC4Y have A	L1 only.)		
Control me	thod	ON/OFF and	P, PI, PD, PIC) control				
Hysteresis		1 to 100°C/°F	= (0.1 to 50.0°C	C/°F) variable				
Proportion:	al band (P)	0.1 to 999.9°	°C/°F					
Integral tim	ne (I)	0 to 9999 se	c					
Derivative	time (D)	0 to 9999 se	C					
Control pe	riod (T)	0.5 to 120.0	sec					
Manual res	set	0.0 to 100.0°	%					
Sampling բ	period	100ms						
Dielectric	AC power	2,000VAC 50	0/60Hz for 1 m	in (between in	nput terminal an	d power termina	al)	
strength	AC/DC power	1,000VAC 50/60Hz for 1 min (between input terminal and power terminal)						
Vibration					5Hz (for 1 min)		direction for 2 ho	ours
Relay	Mechanical		, ,		Over 5,000,000			
life cycle	Electrical	OUT: over 20 AL1/2: over	00,000 operation 300,000 operation	ons (250VAC tions (250VAC	3A resistive load 1A resistive load	d) ad)		
Insulation i	esistance	Over 100MΩ	2 (at 500VDC n	negger)				
Noise imm	unity	Square-wave	e noise by nois	e simulator (p	ulse width 1us)	±2kV R-phase	and S-phase	
Memory re	tention	Approx. 10 y	ears (when us	ing non-volati	le semiconducto	or memory type)		
_	mbient temperature		storage: -20 to					
ment A	mbient humidity		H, storage: 35 t					
Insulation t	уре		lation or reinfo er part: AC pov			electric strength	between the m	neasuring input p
Approval		(€ c 91) us						
Weight ^{*2}								94g Approx. 254 22g) (approx. 155

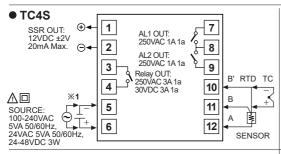
 $[\]frak{x}$ 2: The weight includes packaging. The weight in parenthesis is for unit only.

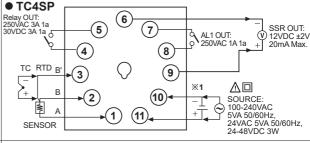
Connections

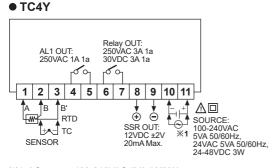
**TC4 Series has selectable control output; Relay output, and SSR drive output. AC/DC power type does not have SSRP function. XUse crimp terminals or teminals of size specified below



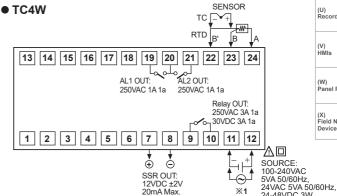








X1: AC power: 100-240VAC 5VA 50/60Hz AC/DC power: 24VAC 5VA 50/60Hz, 24-48VDC 3W



SENSORS CONTROLLERS

MOTION DEVICES

SOFTWARE

(L) Power Controllers

(M) Counters

(N) Timers

(O) Digital Panel Meters

(P) Indicators

(Q) Converters

(R) Digital Display Units

(S) Sensor Controllers

(T) Switching Mode Power Supplies

(U) Recorders

(V) HMIs

(W) Panel PC

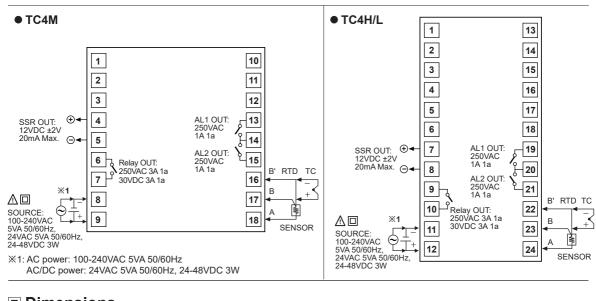
(X) Field Network Devices

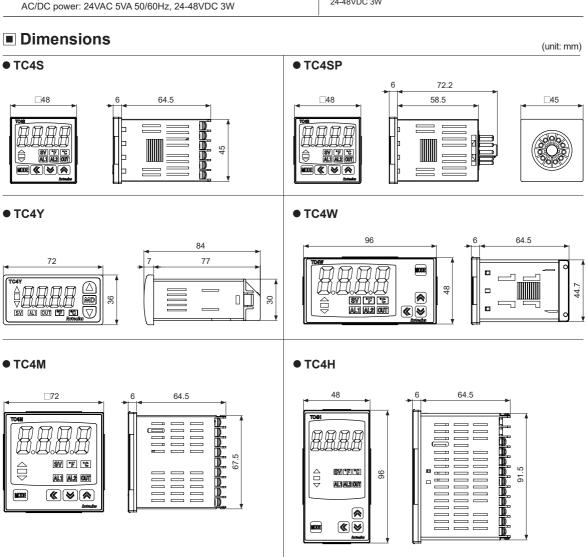
24-48VDC 3W

J-121 **Autonics**

XEnvironment resistance is rated at no freezing or condensation

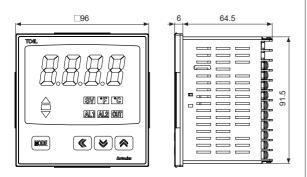
TC Series



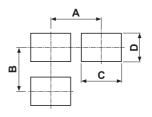


J-122 Autonics

• TC4L



Panel cut-out



Size	А	В	С	D
Model				
TC4S	Min. 65	Min. 65	45 ^{+0.6}	45 0 45 0
TC4SP	Min. 65	Min. 65	45 0 0	45 0 0
TC4Y	Min. 91	Min. 40	68 ^{+0.7}	31.5 +0.5
TC4M	Min. 90	Min. 90	68 ^{+0.7}	68 ^{+0.7}
TC4H	Min. 65	Min. 115	45+0.6	92+0.8
TC4W	Min. 115	Min. 65	92 0 0 0	45 0 45 0
TC4L	Min. 115	Min. 115	92+0.8	92+0.8

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(L) Power Controllers

(N) Timers

(O) Digital Panel Meters

(P) Indicators

(Q) Converters

(R) Digital Display Units

(S) Sensor Controllers

(T) Switching Mode Power Supplies

(U) Recorders

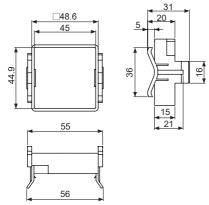
(V) HMIs

(W) Panel PC

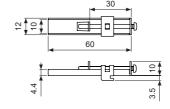
(X) Field Network

Bracket

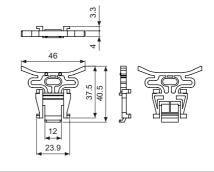
• TC4S/TC4SP Series



• TC4Y Series

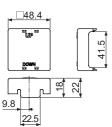


• TC4M, TC4W, TC4H, TC4L Series

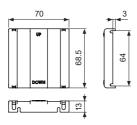


Terminal cover (sold separately)

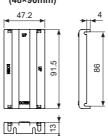
• RSA-COVER (48×48mm)



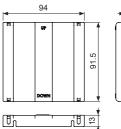
RMA-COVER (72×72mm)



• RHA-COVER (48×96mm)



• RLA-COVER (96×96mm)



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Unit Description



1. Present value (PV) display

- RUN mode: Currently measured value (PV) display.
- Parameter setting mode: Parameter or parameter setting value display.

2. Deviation indicator, Auto-tuning indicator

It shows current temperature (PV) deviation based on set temperature (SV) by LED.

No.	PV deviation temp.	Deviation display
1	Over 2°C	indicator ON
2	Below ±2°C	indicator ON
3	Under -2°C	▼ indicator ON

The deviation indicators $(\blacktriangle, \blacksquare, \blacktriangledown)$ flash by every 1 sec when operating auto tuning.

3. Set temperature (SV) indicator

Press any front key once to check or change current set temperature (SV), the set temperature (SV) indicator is ON and preset set value is flashed.

4. Temperature unit (°C/°F) indicator

It shows current temperature unit.



5. Control/alarm output indicator

 OUT: It will turn ON when control output (Main Control Output) is ON.

※In case of CYCLE/PHASE control of SSR drive output, it will turn ON when MV is over 3.0%. (only for AC voltage type)

• AL1/AL2: It will light up when alarm output Alarm 1/ Alarm 2 are on.

6. MODE kev

Used when entering into parameter group, returning to RUN mode, moving parameter, and saving setting values.

7. Adjustment

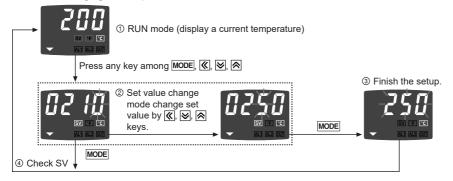
Used when entering into set value change mode, digit moving and digit up/down.

8. FUNCTION key

Press 對+A keys for 3 sec to operate function (RUN/ STOP, alarm output cancel, auto-tuning) set in inner parameter [네 - 년].

SV Setting

XIn case of changing set temperature from 210°C to 250°C.

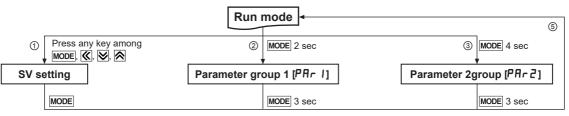


Parameter Reset

Reset all parameters as factory default. Hold the front keys for 5 sec, to enter parameter reset [n t] parameter. Select 'J£5' and all parameters are reset as factory default. Select 'no' and previous settings are maintained. If setting parameter lock [LoC] or processing auto-tuning, parameter reset is unavailable. (except TC4Y Series)

J-124 Autonics

Parameter Group



AL1 alarm temperature

AL2 alarm temperature

AL2 alarm temperature

AL3 alarm temperature

Auto tuning

Proportional band

I Integral time

Derivative time

Manual reset
(Normal deviation correction)

H 15 ON/OFF control hysteresis

X1: It is not displayed for AC/DC power model (TC4□-□2R).

XIf no key entered for 30 sec, it returns to RUN mode automatically and the set value of parameter is not be saved.

X[This parameter might not be displayed depending on other parameter settings.

- ① Press any key once in RUN mode, it advances to set value setting group.
- ② Press MODE key over 2 sec in RUN mode, it advances to parameter group 1.
- $\ensuremath{ \textcircled{3}}$ Press $\ensuremath{ \mbox{\tt MODE}}$ key over 4 sec in RUN mode, it advances to parameter group 2.
- 4 First parameter will be displayed on viewer when it advances to the setting group.
- ⑤ Press MODE key over 3 sec in the setting group, it returns to RUN mode.
 ※Exception: Press MODE key once in SV setting group it returns to RUN mode.

XPress MODE key again within a sec after return to RUN mode by press MODE key over 3 sec, it advances to the first parameter of previous setting group.

※Parameter setup



- Set parameter as the above considering parameter relation of each setting group.
- Check parameter set value after change parameter of setting group 2.

XIndicator model (TC4□-N□N)displays shaded parameter (■■) of parameter group 2.

※Alarm operation mode [月L - 1, 月L - 2] parameter of parameter group 2 is decided whether to display according by alarm output type.

ЖIf alarm operation mode [Я∟ - 1, Я∟ - ∂] of parameter group 2 is set to Я⊼О._ / 5ЬЯ.□ / ∟ЬЯ.□, ЯНУ5 parameter is not displayed.

Input type Uni E Temperature unit n-b Input correction Input digital filter SV low-limit value SV high-limit value - F L Control output operation -ād Control type Control output oUL 55r.ñ SSR drive output method*1 Control cycle AL1 alarm operation mode AL - 2 AL2 alarm operation mode Alarm output hysteresis L b R.E LBA monitoring time Ь Я.Ь LBA detection range ď Digital input key Control output MV in case of Er.nu input break error Parameter lock

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(J) Temperature Controllers

> () SRs

(L) Power Controllers

M) counters

(N)

(O) Digital Panel Meters

(P) Indicators

(Q) Converters

(R) Digital Display Units

(S) Sensor

Sensor Controllers

(T) Switching Mode Power Supplies

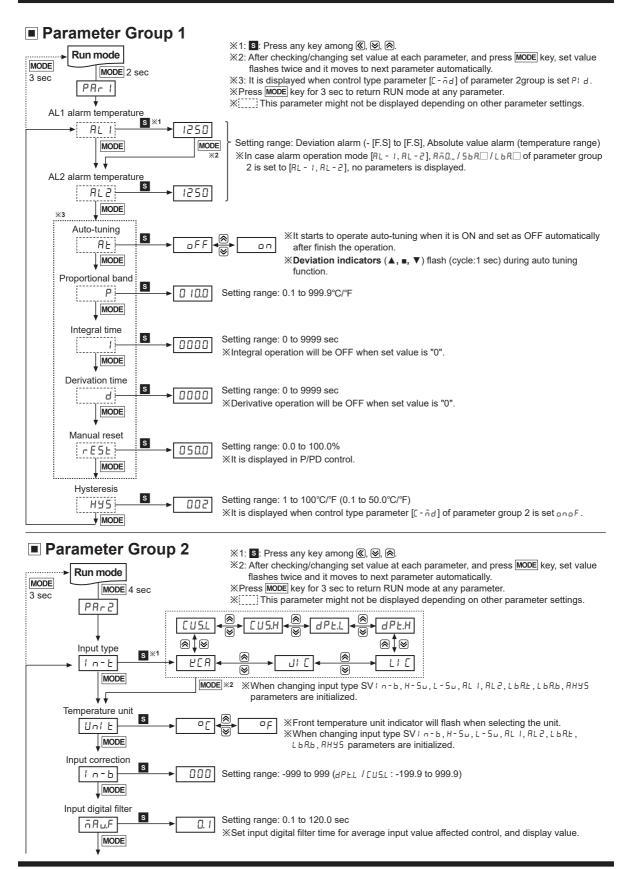
(U) Recorders

. .

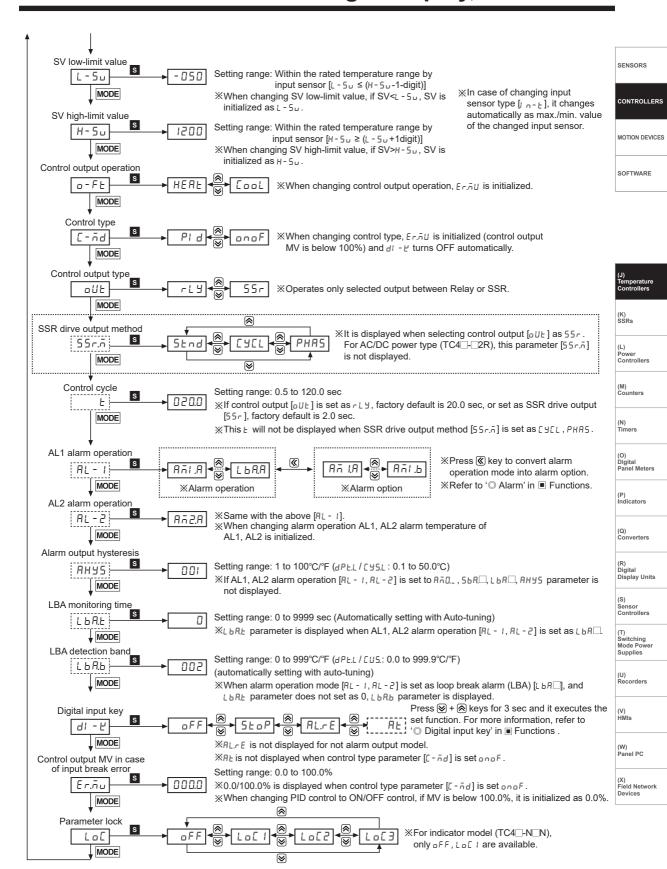
(IAD

(X) Field Network

Autonics J-125



J-126 Autonics



Autonics J-127

Input sensor		Display	Input range (°C)	Input range (°F)
	K(CA)	FCB	-50 to 1200	-58 to 2192
Thermocouple	J(IC)	JI [-30 to 500	-22 to 932
	L(IC)	LIE	-40 to 800	-40 to 1472
	DPt100Ω	dPt.H	-100 to 400	-148 to 752
RTD	DF(10002	dPt.L	-100.0 to 400.0	-148.0 to 752.0
KID	0500	C U 5.H	-50 to 200	-58 to 392
	Cu50Ω	C U 5.L	-50.0 to 200.0	-58.0 to 392.0

■ Factory Default

SV setting

Parameter	Factory default
_	0

Parameter group 1

	,
Parameter	Factory default
AL I	1250
AL2	1630
AF	oFF
Р	0 10.0
1	0000
В	0000
rE5t	050.0
H95	002

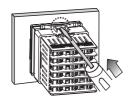
• Parameter group 2

	<u> </u>		
Parameter	Factory default	Parameter	Factory default
In-E	FCB	E	020.0
Uni E	°C	AL-I	RōLB
In-b	0000	UL-1	חחו.ח
⊼Ru.F	000.1	AL-5	RAZ.R
L-5u	-050	AH45	0001
H-5u	1500	L b R.E	0000
o-FŁ	HERL	L 6 R.6	005
[-ñd	PId	91 - F	StoP
oUL	r L H	Er.ñu	0 0 0.0
55r.ñ	Stnd	LoC	oFF

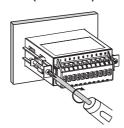
 \times AC/DC power type has no SSR drive output method [55 $_{\text{c.r.}}$] and supports only ON/OFF output when selecting 55 $_{\text{c}}$ in control output [$_{\text{d}}$ U $_{\text{b}}$].

Mounting

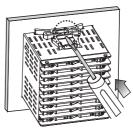
● TC4S/SP (48×48mm) Series



◆ TC4Y (72×36mm) Series



Other Series



*Mount the product on the panel, fasten bracket by pushing with tools as shown above. (In case of TC4Y, fasten bolts for bracket.)

J-128 Autonics

Functions

Alarm Alarm option operation

Set both alarm operation and alarm option by combining Each alarm operates individually in two alarm output models. When the current temperature is out of alarm range, alarm clears automatically. If alarm option is alarm latch or alarm latch and standby sequence 1/2, press digital input key(⊌+ ≥ 3 sec, digital input key[dl - L] of Parameter group 2 set as AL. - E), or turn OFF the power and turn ON to clear alarm.

Alarm operation

Mode	Name	Alarm operation	Description
8 ñ O	_	_	No alarm output
Aŭ I.□	Deviation high-limit alarm	OFF	If deviation between PV and SV as high-limit is higher than set value of deviation temperature, the alarm output will be ON.
Aŭ2.□	Deviation low-limit alarm	ON H OFF ON HOFF ON HOFF SV 90°C 100°C Lower deviation: Set as 10°C ON HOFF SV PV 100°C 110°C Lower deviation: Set as -10°C	If deviation between PV and SV as low-limit is higher than set value of deviation temperature, the alarm output will be ON.
A ō 3.□	Deviation high/low-limit alarm	ON H OFF H ON ON SV PV 90°C 100°C 110°C High/Lower deviation: Set as 10°C	If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be ON.
Ялч.	Deviation high/low-limit reserve alarm	ON H OFF H ON SV 90°C 100°C 110°C High/Lower deviation: Set as 10°C	If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be OFF.
A ō 5.□	Absolute value high limit alarm	OFF H ON PV SV 90°C 100°C Absolute-value Alarm: Set as 90°C OFF H ON SV PV 100°C 110°C 100°C 110°C Absolute-value Alarm: Set as 91°C Set as 91°C	If PV is higher than the absolute value, the output will be ON.
A ē 6.□	Absolute value low limit alarm	ON H OFF ON H OFF ON H OFF SV PV 90°C 100°C 100°C 110°C Absolute-value Alarm: Set as 90°C Set as 110°C	If PV is lower than the absolute value, the output will be ON.
5 <i>bR</i> .□	Sensor break Alarm	_	It will be ON when it detects sensor disconnection.
∟ЬЯ.□	Loop break Alarm	<u> </u>	It will be ON when it detects loop break.

Ж H: Alarm output hysteresis [ЯНЧ5]

Alarm option

Mode	Name	Description
A⊼□.A	Standard alarm	If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.
Añ □.b	Alarm latch	If it is an alarm condition, alarm output is ON and maintains ON status. (Alarm output HOLD)
Ay⊡'C	Standby sequence 1	First alarm condition is ignored and from second alarm condition, standard alarm operates. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.
R⊼ □.d	Alarm latch and standby sequence 1	If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, alarm latch operates.
Añ □.E	Standby sequence 2	First alarm condition is ignored and from second alarm condition, standard alarm operates. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, standard alarm operates.
Aā⊡.F	Alarm latch and standby sequence 2	Basic operation is same as alarm latch and standby sequence 1. It operates not only by power ON/OFF, but also alarm setting value, or alarm option changing. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, alarm latch operates.

^{**}Condition of re-applied standby sequence for standby sequence 1, alarm latch and standby sequence 1: Power ON Condition of re-applied standby sequence for standby sequence 2, alarm latch and standby sequence 2. Power ON, changing set temperature, alarm temperature [AL 1, AL 2] or alarm operation [AL - 1, AL - 2], switching STOP mode to RUN mode.

The function that alarm output will be ON when sensor is not connected or when sensor's disconnection is detected during temperature controlling. You can check whether the sensor is connected with buzzer or other units using alarm output contact. It is selectable between standard alarm [56RR], or alarm latch [56Rb].

CONTROLLERS

SENSORS

MOTION DEVICES

SOFTWARE

Power Controllers

(O) Digital Panel Meters

(P) Indicators

(Q) Converters

(R) Digital Display Units

(S) Sensor Controllers

(T) Switching Mode Power Supplies

(U) Recorders

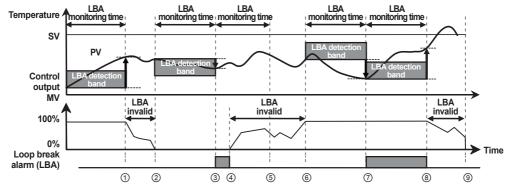
(W) Panel PC

(X) Field Network

J-129 **Autonics**

O Loop break alarm (LBA)

It checks control loop and outputs alarm by temperature change of the subject. For heating control (cooling control), when control output MV is 100% (0% for cooling control) and PV is not increased over than LBA detection band [L b Rb] during LBA monitoring time [L b Rb], or when control output MV is 0% (100% for cooling control) and PV is not decreased below than LBA detection band [L b Rb] during LBA monitoring time [L b Rb], alarm output turns ON.

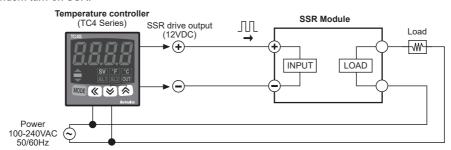


Start control to ①	When control output MV is 0% and PV is not decreased below than LBA detection band [L b Rb] during LBA monitoring time [L b Rb]
① to ②	The status of changing control output MV (LBA monitoring time is reset.)
② to ③	When control output MV is 0% and PV is not decreased below than LBA detection band [ኒ ե Rե] during LBA monitoring time [ኒ ե Rէ], loop break alarm (LBA) turns ON after LBA monitoring time.
3 to 4	Control output MV is 0% and loop break alarm (LBA) turns and maintains ON.
4 to 6	The status of changing control output MV (LBA monitoring time is reset.)
⑥ to ⑦	When control output MV is 100% and PV is not increased over than LBA detection band [L b Rb] during LBA monitoring time [L b Rb], loop break alarm (LBA) turns ON after LBA monitoring time.
⑦ to ⑧	When control output MV is 100% and PV is increased over than LBA detection band [ኒ ይብይ] during LBA monitoring time [ኒ ይብይ] loop break alarm (LBA) turns OFF after LBA monitoring time.
8 to 9	The status of changing control output MV (LBA monitoring time is reset.)

When executing auto-tuning, LBA detection band [L b Rb] and LBA monitoring time are automatically set based on auto tuning value. When AL1, AL2 alarm operation [RL - I, RL - 2] is set as loop break alarm (LBA) [L b R□], LBA detection band [L b Rb] and LBA monitoring time [L b Rb] parameter is displayed.

SSR drive output function (SSRP function) [55 r.⊼]

- SSRP function is selectable one of standard ON/OFF control, cycle control, phase control by utilizing standard SSR drive output
- Realizing high accuracy and cost effective temperature control as linear output(cycle control and phase control).
- Select one of standard ON/OFF control [5½ nd], cycle control [5½ L], phase control [7485] at [55 nd] parameter of Parameter group 2. For cycle control, connect zero cross turn-on SSR or random turn-on SSR. For phase control, connect random turn-on SSR.



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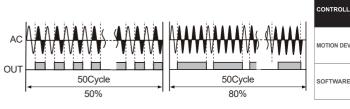
● Standard ON/OFF control mode [5tnd]

A mode to control the load in the same way as Relay

(ON: output level 100%, OFF: output level 0%)

● Cycle control [[Ӌ[L]]

A mode to control the load by repeating output ON / OFF according to the rate of output within setting cycle. Having improved ON / OFF noise feature by Zero Cross type.

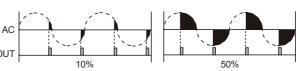


OFF



OFF

SENSORS



● Phase control [PHR5]

A mode to control the load by controlling the phase within AC half cycle. Serial control is available.

RANDOM Turn-on type SSR must be used for this mode.

- When setting RŁ parameter to □ n, front temperature unit display (°C or °F) indicator will be flickering during Auto tuning. After completing auto tuning, temperature unit display indicator returns to normal operation and RE parameter automatically becomes $[\Box \cap \to \Box FF]$.
- Set as of F to stop auto tuning. XIt keeps previous P, I, D set values.
- If SV is changed during auto tuning mode, auto tuning is stopped.
- PID time constants figured out through auto tuning function can be changed.
- If control method [[-nd] is set to onoF, no parameters are displayed.
- Finish auto tuning when [aPEn] error occurs during the operation

XIn case of [□PE□] error, auto tuning operation is not applicable.

Controller itself does not have errors but there may be error by external input temperature sensor.

E.g.)If actual temperature is 80°C but controller displays 78°C, set input correction value [n - b] as 002 and controller displays 80°C.

XAs the result of input correction, if current temperature value (PV) is over each temperature range of input sensor, it displays HHHH or LLLL.

© Input digital filter [กัЯแҒ]

If current temperature (PV) is fluctuating repeatedly by rapid change of input signal, it reflects to MV and stale control is impossible. Therefore, digital filter function stabilizes current temperature value.

•For example, set input digital filter value as 0.4 sec, and it applies digital filter to input values during 0.4 sec and displays this values. Current temperature may be different by actual input value.

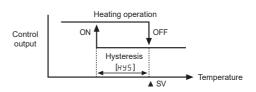
© Control method selection [[-ਜ਼d]

It is selectable PID, ON/OFF control.

- In case of ON/OFF [□□□F] mode, Hysteresis [HIJ5] parameter is displayed.
- In case of PID [PI d] mode, Proportional band [P], Integral time [1], and Derivative time [1] parameters are displayed.

○ Hysteresis [HY5]

 Set control output ON / OFF interval in ON / OFF control mode.



- If Hysteresis is too narrow, hunting (oscillation, chattering) could occur due to external noise.
- In case of ON / OFF control mode, even if PV reaches stable status, there still occurs hunting. It could be due to Hysteresis [HY5] SV, load's response characteristics or sensor's location. In order to reduce hunting to a minimum, it is required to take into following factors consideration when designing temp. controlling; proper Hysteresis [HY5], heater's capacity, thermal characteristics, sensor's response and location.

© Temperature unit selection [⊔n/ 上]

- · A function to select display temperature unit
- Unit display indicator will be ON when converting temperature unit.

Controllers	(J) Temperature Controllers
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(L) Power Controllers

(N) Timers

(O) Digital Panel Meters

(P) Indicators

(Q) Converters

(R) Digital Display Units

(S) Sensor Controllers

(T) Switching Mode Powe Supplies

(U) Recorders

(V) HMIs

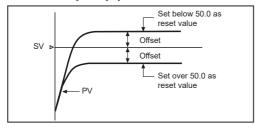
(W) Panel PC

(X) Field Network

J-131 Autonics

When selecting P/PD control mode, certain temperature difference exists even after PV reaches stable status because heater's rising and falling time is inconsistent due to thermal characteristics of controlled objects, such as heat capacity, heater capacity. This temperature difference is called offset and manual reset [r E 5 L] function is to set/correct offset.

- When PV and SV are equal, reset value is 50.0%. After control is stable, PV is lower than SV, reset value is over 50.0% or PV is higher than SV, reset value is below 50.0%.
- Manual reset [- E5 L] by control result



Manual reset function is applicable only to P / PD control mode.

© Control output MV when input sensor line is broken [Ετ.πμ]

The function to set control output MV in case of open error. Users are able to set by ON/OFF setting or MV setting. It executes control output by set MV regardless of ON/OFF or PID control output.

○ Cool / Heat function [□ - F +]

Generally there are two ways to control temperature, one (Heat-function) is to heat when PV is getting down (Heater). The other (Cool-function) is to cool when PV is getting higher (Freezer).

These functions are operating oppositely when it is ON/ OFF control or proportional control. But in this case PID time constant will be different due to PID time constant will be decided according to control system when it is PID control.

- Cool-function [EaaL] and heat-function [HEAL] must be set correctly according to the application, if set as opposite function, it may cause a fire. (If set cool-function [EaaL] at heater, it will be maintained ON and it may cause a fire.)
- Avoid changing heat-function to cool-function or coolfunction to heat-function when the unit is operating.
- It is impossible to operate both function at once in this unit. Therefore, only one function should be selected only

SV High/Low limit [H-5□ / L-5□]

- It sets SV high/low limit Limit range of using temperature within temperature range for each sensor, user can set/ change set temperature (SV) within SV high limit [H-5□] to SV low limit [L-5□]. (※ L-5□ > H-5□ cannot be set.)
- When changing input type [i n-b], SV high limit [H-5u] and SV low limit [L-5u] of using temperature will be initialized as max./min. value of sensor temperature range automatically.

Parameter		Operation		
OFF	oFF	It does not use digital input key function.		
RUN/STOP	5toP	Pauses control output. Auxiliary output (except loop break alarm, sensor break alarm)except Control output operates as setting. Hold the digital input keys for 3 sec to restart. I		
Clear alarm	AL.r.E	Clears alarm output by force. (only when alarm option is alarm latch, or alarm latch and standby sequence 1/2 .) This function is applied when present value is out of alarm operation range but alarm output is ON. Alarm operates normally right after clearing alarm.		
Auto-tuning	RĿ	Starts/Stops auto-tuning. This function is same as auto-tuning[AE] of parameter group 1. (You can start auto-tuning [AE] of parameter group 1 and stop it by digital input key.) **This parameter AE appears only when control method [E - ād] Parameter group 2 is set as AI d. When control method [E - ād] Parameter group 2 is set as AI d. When control method [E - ād] Parameter group 2 is set as AI d. When control method [E - ād] Parameter group 2 is set as AI d. When control method [E - ād] Parameter group 2 is set as AI d. When control method [E - ād] Parameter group 3 is set as AI d. When control method [E - ād] Parameter group 3 is set as AI d. When control method [E - ād] Parameter group 3 is set as AI d. When control method [E - ād] Parameter group 3 is set as AI d. When control method [E - ād] Parameter group 4 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When control method [E - ād] Parameter group 5 is set as AI d. When con		

A function to prevent changing SV and parameters of each setting group. Parameter setting values are still possible to check when parameter lock is set.

Display	Description
oFF	Lock off
LoCI	Lock parameter group 2
Lo[2	Lock parameter group 1, 2
Lo[3	Lock parameter group 1, 2, SV setting

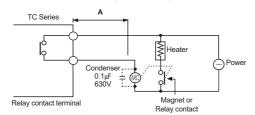
 $\times {}_{\Box}FF$, $L {}_{\Box}E$ | are available only for indicator (TC4 \square -N \square N).

© Error

Display	Description	Troubleshooting
oPEn	Flashes if input sensor is disconnected or sensor is not connected.	Check input sensor state.
нннн	Flashes if measured sensor input is higher than temperature range.	When input is within the rated temperature
LLLL	Flashes if measured sensor input is lower than temperature range.	range, this display disappears.

Output connections

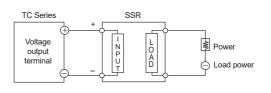
Application of relay output type



Keep **A** length as long as possible when wiring the temperature controller and the load. If wire length of **A** is short, counter electromotive force which occurs from a coil of magnet switch & power relay may flow in power line of the unit, and it may cause malfunction.

If wire length of **A** is short, please connect mylar condensers 104 (630V) on the both ends of "" (magnet coil) to protect electromotive force.

Application of SSR drive output method



※Please use a cooling plate or it may cause the capability deterioration, breakdown of SSR for a long usage.

※Refer to page '◎ SSR drive output function (SSRP function)' for phase/cycle control connections.

(J) Temperature Controllers

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

() SRs

(L) Power Controllers

(M) Counters

(N) Timers

(O) Digital Panel Meters

(P) Indicators

(Q) Converters

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(X) Field Network Devices

Proper Usage

⊚ Simple "error" diagnosis

• When the load (Heater etc) is not operated

Please check operation of the OUT indicator located in front panel of the unit.

If the OUT indicator does not operate, please check the parameter of all programmed mode.

If indicator is operating, please check the output (Relay, SSR drive voltage) after separating output line from the

This is a warning that external sensor is open. Please turn off the power and check the wire state of the sensor. If sensor is not open disconnect sensor line from the unit and short the input +, - terminal. Turn on the power of the unit and check the controller displays room temperature.

If this unit cannot display room temperature, this unit is broken. Please remove this unit and contact our service center. (When the input mode is thermocouple, it is available to display room temperature.)

© Cautions during use

- Follow instructions in 'Cautions during use'. Otherwise, It may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor.

For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length.

For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire.

 Keep away from high voltage lines or power lines to prevent inductive noise.

In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.

Do not use near the equipment which generates strong magnetic force or high frequency noise.

- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the nower
- Do not use the unit for other purpose (e.g. voltmeter, ammeter) but temperature controller.
- ammeter), but temperature controller.

 When changing the input sensor, turn off the power first
 - After changing the input sensor, modify the value of the corresponding parameter.
- 24VAC, 24-48VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- Make a required space around the unit for radiation of heat

For accurate temperature measurement, warm up the unit over 20 min after turning on the power.

- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments.
 ①Indoors

(in the environment condition rated in 'Specifications')

- ②Altitude max. 2,000m
- ③Pollution degree 2

before changing.

4 Installation category II

Autonics J-133